

Student Name:

Student id:

Sect#: Serial #:

QUESTION #	1	2	3	4	TOTAL
MAX POINTS	10	12	17	14	
POINTS EARNED					

University of Bahrain

College of Information Technology  
Department of Computer ScienceITCS332: Organization of Programming Languages **SECOND TEST** **Date: MAY 4, 2015**

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**QUESTION ONE:****[5+5 pts]**

- a) What will be printed after executing the following C++ code?

```

static int t=5;
void funX()
{ static int x1 = 4;
  int f = x1 * t;
  int *p = new int(5);
  x1 = x1 + t - *p;
  cout << x1 << '\t' << f << endl;
  t++; *p = *p + 2;
  delete p;
}
int main ()
{
  funX();
  cout << t << endl;
  funX();
}

```

<b>4</b>	<b>20</b>
<b>6</b>	
<b>5</b>	<b>24</b>

- b) Consider the following Ada-like code. The value of n printed by
- print (n)**
- :

Procedure **main** is

n: integer ;

Procedure **sub1** is1) Under static -scoped rules is **30+17= 47**

begin

n = n + 17 ; **print (n)** ;

end ;

Procedure **sub2** is2) Under dynamic-scoped rules is **14+17= 31**

n : integer;

begin

n = 14 ; **sub1** ; n = n + 5;

end ;

begin

n = 30 ; **sub2** ;

end ;

**QUESTION TWO:****[8+4 pts]****Part #1**

- 1) Prolog operates in two modes *entry* and *query* mode.
- 2) The process of assigning temporary values to variables to allow unification to succeed is called *instantiation*. The process of finding useful values for variables in propositions that allows matching process to succeed is called *unification*.
- 3) The process that works on all subgoals of a given goal in parallel is called *breadth-first search*. The process of finding a complete proof for the first subgoal before working on others is called *depth-first search*.
- 4) The prolog query  $?- [b, 34, 5 | T] = [b, 34, 5, 66, b]$ . produces  $T = [66, b]$
- 5) The prolog query  $?- [[cat, X] | Y] = [[cat, black], [dog, rat], lion]$ . produces  $X = black,$  and  $Y = [[dog, rat], lion]$ .

```
myst([], 0).
```

```
myst([X|Y], R) :- myst(Y, U), R is U+1.
```

- 6) The prolog query  $?- myst([7, 4], 6, 2, 3, [8, -9], 11, [-2], T)$ . produces  $T = 7$ .

**Part #2**

- 7) Write Prolog predicate(s) named "**most**" that displays the last item in a given list as shown in the following queries.

```
?- most([-5], T).  
T = -5.
```

```
?- most([1, 10, 20], X).  
X = 20.
```

```
?- most([1, [10, 20], 8, [7, 5, -1]], U).  
U = [7, 5, -1].
```

***most ([ X ], X).***

***most ([ \_ | T ], R) :- most (T, R).***

**QUESTION THREE :****[17 pts]****Part #1****[6 pts]**

- 1) List 2 differences between stack-dynamic and heap-dynamic arrays. **[2 pts]**
  - a) Stack-dynamic arrays are allocated on the **stack**, while the heap-dynamic arrays are allocated on the **heap**.
  - b) Heap-dynamic arrays **can grow and shrink**, while stack-dynamic arrays **can not**.
- 2) Give one advantage and one disadvantage of long names. **[2 pts]**
  - a) **The advantage is** that they are **meaningful and improve the readability**.
  - b) **The disadvantage is** that they are **wasting the memory space of the symbol table**.
- 3) In C++, the main disadvantage of stack-dynamic variables is large execution time. Justify. **[1 pts]**

**Execution time** is wasted for **allocating stack-dynamic variables** on every entry of the defining block and for **deallocating them on every exit** from the defining block.
- 4) What is the difference between a keyword and a reserved word? **[1 pts]**

**keyword** can be redefined by the programmer and the **reserved word** cannot be redefined.

**Part #2****[11 pts]**

- 1) In C++, the base address = 1250 and "double U[220];"  
The address of the element  $U[80] = 1250 + (80-0)*8$ .
- 2) In C++, the base address = 3200 and `short x[80][60];` the address of `x[17][24]` is  **$3200 + 2 * [(17-0)*60 + (24-0)]$** .
- 3) The dynamic length strings are implemented using **Linked Lists** or **Adjacent memory Cells**.
- 4) In programming languages, aliases are created using **references** or **parameters**.
- 5) A data type is a **collection of data values (objects)** plus **a set of predefined operations that can be applied on those objects**.
- 6) In C++, the static scope is created for every **block** and **function**.
- 7) The index type in any array reference is decided by **Language Designer**. The storage size of a given data type is specified by **Language Implementer**.
- 8) For multidimensional arrays, using row-major or column-major ordering of elements is decided by **Language Implementer**. The code to access an array element is generated by the **Compiler**.
- 9) The two major disadvantages of static variables are: **They do not support recursion** and **Low efficient use of memory space**.
- 10) The two disadvantages of dynamic length string implemented as a linked list are: **complex and slow string operations** and **pointer space overhead**.
- 11) Name two character string design issues: **string type: primitive or structured** and **string length: static or dynamic**.

**QUESTION FOUR:** Study the following C\_like code and answer ALL questions below: [14 pts]

```
65) static int z[64];
66) void funA(double size)
67) {   int w[64];       int y[size];
68)     int x[]={10,15,-24,-88,77};
69)     int *f = new int[24];
        ... ..
77)     sqrt(z[10]);
        ... ..

85) }
86) void char funB()
87) {   char *uptr = new char('U');
88)     static float d = -4.75;
89)     double sum; ... ..
100) }
```

- 1) The scope of a array **x** is **from line #68 in function funA to line #85.**
- 2) The scope of a variable **d** is **from line #88 in function funB to line #100.**
- 3) The type of a pointer variable **uptr** is **stack-dynamic**
- 4) The type of the object (variable) pointed to by **uptr** is **explicit-heap dynamic**
- 5) The lifetime of a variable **d** begins when **the function funB is loaded first time** and ends when **the entire program terminates.**
- 6) The array **f** is allocated space **on the heap** of program memory, while the array **w** is allocated space **on the stack.**
- 7) The array **z** is bound to storage during the **loading** time of the program. The call to the standard function **sqrt** in function **funA** is bound to its code at the **linking** time.
- 8) The type of array **f** is **fixed-heap dynamic**
- 9) The type of array **w** is **fixed stack-dynamic.**
- 10) The type of array **y** is **stack-dynamic**
- 11) The type of array **z** is **static**
- 12) The lifetime of array **z** begins when **the program is loaded** and ends when **the entire program terminates.**
- 13) The lifetime of a variable **sum** begins whenever **the function funB is called** and ends whenever **the function funB is terminated (return).**
- 14) The lifetime of a variable **uptr** begins whenever **the function funB is called** and ends whenever **the function funB is terminated (return).**